



FEATURES

- Acquire and track 65 satellites simultaneously
- Venus 6 correlators
- Signal detection better than -160dBm
- Reacquisition sensitivity –155dBm
- Cold start < 30 seconds at –147dBm
- Hot start < 1sec under open sky
- 5m CEP accuracy
- SBAS (WAAS, EGNOS) support
- Support A-GPS function
- < 30mA
- Built-in passive antenna
- Flash-memory based
- Smallest Dimension: 20 x 20 x 8.8 mm

GT-723F Fast Acquisition Enhanced Sensitivity 65 Channel GPS Smart Antennae

The GT-723F is a compact all-in-one GPS module solution intended for a broad range of Original Equipment Manufacturer (OEM) products, where fast and easy system integration and minimal development risk is required.

The receiver continuously tracks all satellites in view and provides accurate satellite positioning data. The GT-723F is optimized for applications requiring high-performance, low cost, and maximum flexibility; suitable for a wide range of OEM configurations including handhelds, sensors, asset tracking, PDA-centric personal navigation system, and vehicle navigation products.

Its 65 parallel channels and Venus 6 search bins provide fast satellite signal acquisition and short startup time. Acquisition sensitivity of –155dBm and tracking sensitivity of –160dBm offers good navigation performance even in urban canyons having limited sky view..

Satellite-based augmentation systems, such as WAAS and EGNOS, are supported to yield improved accuracy. Besides it also supports A-GPS function and fixed in the short time.

RS232-level serial interface are provided on the interface connector. Supply voltage of 3.0V~6.0V is supported.

Users can modify NMEA sentences or Binary code by the extra flash memory.



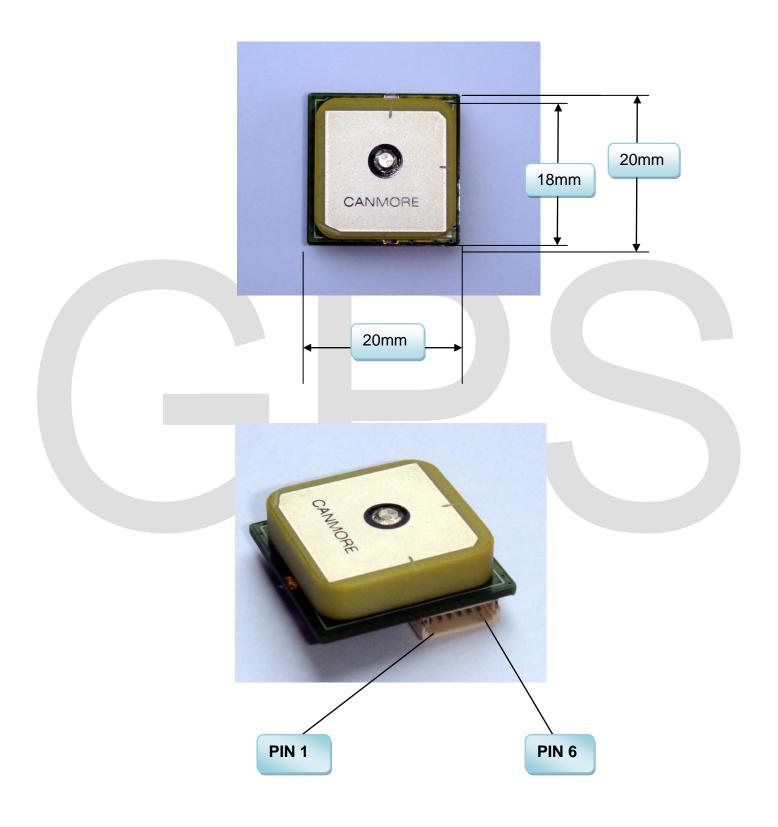
TECHNICAL SPECIFICATIONS

| Receiver Type | 65 parallel channels, L1 C/A code |
|---------------------------|---|
| Accuracy | Position2.5m CEPVelocity0.1m/secTime250ns |
| Startup Time (average) | < 1sec hot start < 30sec cold start |
| Signal Reacquisition | 1s |
| Sensitivity | -155dBm acquisition -160dBm tracking |
| A-GPS | Support PromptFix [®] AGPS |
| Update Rate | 1Hz standard |
| | (5Hz/10Hz special order) |
| Dynamics | 4G (39.2m/sec ₂) |
| Operational Limits | Altitude < 18,000m or velocity < 515m/s (COCOM limit, either may be exceeded but not both) |
| Serial Interface | 3.3V RS232 level |
| Protocol | NMEA-0183 V3.01 |
| | GPGGA, GPGLL, GPGSA, GPGSV, GPRMC, GPVTG, GPZDA ,9600 baud, 8, N, 1 |
| Datum | Default WGS-84 |
| | User definable |
| Input Voltage | 3.0V~6.0V |
| Input Current | ~50mA acquisition ~30mA tracking |
| Dimension | 20.0mm L x 20.0mm W x 8.8mm H |
| Weight: | 5g |
| Operating Temperature | -40°C ~ +82°C |
| Humidity | 5% ~ 95% |

2



Mechanical Dimension

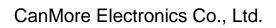


GT-720F Lateral View



PINOUT DESCRIPTION

| Pin Number | Signal Name | Description |
|------------|-------------------|---|
| 1 | Ground | Power and signal ground |
| 2 | Power | 3.0V ~ 5.0V DC input |
| 3 | Serial Data In 2 | Asynchronous serial input at RS-232 level, to input command message |
| 4 | Serial Data Out 2 | Asynchronous serial output at RS-232 level, to output NMEA message |
| 5 | Serial Data In 1 | Asynchronous serial input at TTL level, to input command message |
| 6 | Serial Data Out 2 | Asynchronous serial output at TTL level, to output NMEA message |





NMEA Messages

The serial interface protocol is based on the National Marine Electronics Association's NMEA 0183 ASCII interface specification. This standard is fully define in "NMEA 0183, Version 3.01" The standard may be obtained from NMEA, www.nmea.org

GGA - GPS FIX DATA

Time, position and position-fix related data (number of satellites in use, HDOP, etc.).

Format:

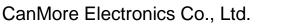
\$GPGGA,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,M,<10>,M,<11>,<12>,*<13><CR><LF>

Example:

\$GPGGA,104549.04,2447.2038,N,12100.4990,E,1,06,01.7,00078.8,M,0016.3,M,,*5C<CR><LF>

| Field | Example | Description |
|-------|------------|--|
| 1 | 104549.04 | UTC time in hhmmss.ss format, 000000.00 ~ 235959.99 |
| 2 | 2447.2038 | Latitude in ddmm.mmmm format Leading zeros transmitted |
| 3 | N | Latitude hemisphere indicator, 'N' = North, 'S' = South |
| 4 | 12100.4990 | Longitude in dddmm.mmmm format Leading zeros transmitted |
| 5 | E | Longitude hemisphere indicator, 'E' = East, 'W' = West |
| 6 | 1 | Position fix quality indicator 0: position fix unavailable 1: valid position fix, SPS mode 2: valid position fix, differential GPS mode |
| 7 | 06 | Number of satellites in use, 00 ~ 12 |
| 8 | 01.7 | Horizontal dilution of precision, 00.0 ~ 99.9 |
| 9 | 00078.8 | Antenna height above/below mean sea level, -9999.9 ~ 17999.9 |
| 10 | 0016.3 | Geoidal height, -999.9 ~ 9999.9 |
| 11 | | Age of DGPS data since last valid RTCM transmission in xxx format (seconds) NULL when DGPS not used |
| 12 | | Differential reference station ID, 0000 ~ 1023 NULL when DGPS not used |
| 13 | 5C | Checksum |

Note: The checksum field starts with a '*' and consists of 2 characters representing a hex number. The checksum is the exclusive OR of all characters between '\$' and '*'.





GLL - LATITUDE AND LONGITUDE, WITH TIME OF POSITION FIX AND STATUS

Latitude and longitude of current position, time, and status.

Format:

\$GPGLL,<1>,<2>,<3>,<4>,<5>,<6>,<7>*<8><CR><LF>

Example:

\$GPGLL,2447.2073,N,12100.5022,E,104548.04,A,A*65<CR><LF>

| Field | Example | Description |
|-------|------------|---|
| 1 | 2447.2073 | Latitude in ddmm.mmmm format |
| | | Leading zeros transmitted |
| 2 | N | Latitude hemisphere indicator, 'N' = North, 'S' = South |
| 3 | 12100.5022 | Longitude in dddmm.mmmm format Leading zeros transmitted |
| 4 | E | Longitude hemisphere indicator, 'E' = East, 'W' = West |
| 5 | 104548.04 | UTC time in hhmmss.ss format, 000000.00 ~ 235959.99 |
| 6 | А | Status, 'A' = valid position, 'V' = navigation receiver warning |
| 7 | A | Mode indicator 'N' = Data invalid 'A' = Autonomous 'D' = Differential 'E' = Estimated |
| 8 | 65 | Checksum |



GSA - GPS DOP AND ACTIVE SATELLITES

GPS receiver operating mode, satellites used for navigation, and DOP values.

Format:

Example:

\$GPGSA,A,3,26,21,,,09,17,,,,,,10.8,02.1,10.6*07<CR><LF>

| Field | Example | Description |
|-------|--------------------|---|
| 1 | A | Mode, 'M' = Manual, 'A' = Automatic |
| 2 | 3 | Fix type, 1 = not available, 2 = 2D fix, 3 = 3D fix |
| 3 | 26,21,,,09,17,,,,, | PRN number, 01 to 32, of satellite used in solution, up to 12 transmitted |
| 4 | 10.8 | Position dilution of precision, 00.0 to 99.9 |
| 5 | 02.1 | Horizontal dilution of precision, 00.0 to 99.9 |
| 6 | 10.6 | Vertical dilution of precision, 00.0 to 99.9 |
| 7 | 07 | Checksum |

GSV - GPS SATELLITE IN VIEW

Number of satellites in view, PRN number, elevation angle, azimuth angle, and C/No. Only up to four satellite details are transmitted per message. Additional satellite in view information is sent in subsequent GSV messages.

Format:

\$GPGSV,<1>,<2>,<3>,<4>,<5>,<6>,<7>,...,<4>,<5>,<6>,<7> *<8><CR><LF>

Example:

\$GPGSV,2,1,08,26,50,016,40,09,50,173,39,21,43,316,38,17,41,144,42*7C<CR><LF> \$GPGSV,2,2,08,29,38,029,37,10,27,082,32,18,22,309,24,24,09,145,*7B<CR><LF>

| Field | Example | Description |
|-------|---------|---|
| 1 | 2 | Total number of GSV messages to be transmitted |
| 2 | 1 | Number of current GSV message |
| 3 | 08 | Total number of satellites in view, 00 ~ 12 |
| 4 | 26 | Satellite PRN number, GPS: 01 ~ 32, SBAS: 33 ~ 64 (33 = PRN120) |
| 5 | 50 | Satellite elevation number, 00 ~ 90 degrees |
| 6 | 016 | Satellite azimuth angle, 000 ~ 359 degrees |
| 7 | 40 | C/No, 00 ~ 99 dB Null when not tracking |
| 8 | 7C | Checksum |



RMC - RECOMMANDED MINIMUM SPECIFIC GPS/TRANSIT DATA

Time, date, position, course and speed data.

Format:

\$GPRMC,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,<10>,<11>,<12>*<13><CR><LF>

Example:

\$GPRMC,104549.04,A,2447.2038,N,12100.4990,E,016.0,221.0,250304,003.3,W,A*22<CR><L F>

| Field | Example | Description |
|-------|------------|---|
| 1 | 104549.04 | UTC time in hhmmss.ss format, 000000.00 ~ 235959.99 |
| 2 | A | Status, 'V' = navigation receiver warning, 'A' = valid position |
| 3 | 2447.2038 | Latitude in dddmm.mmmm format Leading zeros transmitted |
| 4 | N | Latitude hemisphere indicator, 'N' = North, 'S' = South |
| 5 | 12100.4990 | Longitude in dddmm.mmmm format Leading zeros transmitted |
| 6 | E | Longitude hemisphere indicator, 'E' = East, 'W' = West |
| 7 | 016.0 | Speed over ground, 000.0 ~ 999.9 knots |
| 8 | 221.0 | Course over ground, 000.0 ~ 359.9 degrees |
| 9 | 250304 | UTC date of position fix, ddmmyy format |
| 10 | 003.3 | Magnetic variation, 000.0 ~ 180.0 degrees |
| 11 | W | Magnetic variation direction, 'E' = East, 'W' = West |
| 12 | A | Mode indicator 'N' = Data invalid 'A' = Autonomous 'D' = Differential 'E' = Estimated |
| 13 | 22 | Checksum |



VTG - COURSE OVER GROUND AND GROUND SPEED

Velocity is given as course over ground (COG) and speed over ground (SOG).

Format:

GPVTG,<1>,T,<2>,M,<3>,N,<4>,K,<5>*<6><CR><LF>

Example:

\$GPVTG,221.0,T,224.3,M,016.0,N,0029.6,K,A*1F<CR><LF>

| Field | Example | Description |
|-------|---------|---|
| 1 | 221.0 | True course over ground, 000.0 ~ 359.9 degrees |
| 2 | 224.3 | Magnetic course over ground, 000.0 ~ 359.9 degrees |
| 3 | 016.0 | Speed over ground, 000.0 ~ 999.9 knots |
| 4 | 0029.6 | Speed over ground, 0000.0 ~ 1800.0 kilometers per hour |
| 5 | A | Mode indicator 'N' = Data invalid 'A' = Autonomous 'D' = Differential 'E' = Estimated |
| 6 | 1F | Checksum |

ZDA TIME AND DATE

Format:

\$GPZDA,<1>,<2>,<3>,<4>,<5>,<6>*<7><CR><LF>

Example:

```
$GPZDA,104548.04,25,03,2004,,*6C<CR><LF>
```

| Field | Example | Description |
|-------|-----------|---|
| 1 | 104548.04 | UTC time in hhmmss.ss format, 000000.00 ~ 235959.99 |
| 2 | 25 | UTC time: day (01 31) |
| 3 | 03 | UTC time: month (01 12) |
| 4 | 2004 | UTC time: year (4 digit year) |
| 5 | | Local zone hour Not being output by the receiver (NULL) |
| 6 | | Local zone minutes Not being output by the receiver (NULL) |
| 7 | 6C | Checksum |



Binary Messages

See Binary Message Protocol User's Guide for detailed descriptions.

CanMore Electronics Co., LTD.

No. 40, Chenggonh 5th St., Jhubei City Hsinchu County, 302, Taiwan

Phone +886 3 6586046 Fax +886 3 6583940 Email: sales@canmore.com.tw Website:http:// www.canmore.com.tw http://canmorecorp.trustpass.alibaba.com/

© 2000 CanMore Electronics Co., Ltd. All rights reserved.

Not to be reproduced in whole or part for any purpose without written permission of CanMore Electronics Co., Ltd. ("CMEC") Information provided by CMEC is believed to be accurate and reliable. These materials are provided by CMEC as a service to its customers and may be used for informational purposes only. CMEC assumes no responsibility for errors or omissions in these materials, nor for its use. CMEC reserves the right to change specification at any time without notice.

These materials are provides "as is" without warranty of any kind, either expressed or implied, relating to sale and/or use of CMEC products including liability or warranties relating to fitness for a particular purpose, consequential or incidental damages, merchantability, or infringement of any patent, copyright or other intellectual property right. CMEC further does not warrant the accuracy or completeness of the information, text, graphics or other items contained within these materials. CMEC shall not be liable for any special, indirect, incidental, or consequential damages, including without limitation, lost revenues or lost profits, which may result from the use of these materials.

CMEC products are not intended for use in medical, life-support devices, or applications involving potential risk of death, personal injury, or severe property damage in case of failure of the product.

